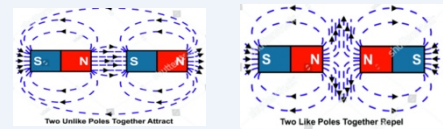


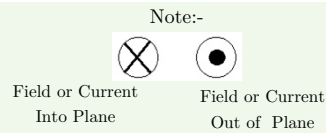
The Basics

- Magnetic fields are created by moving charges e.g. a moving particle or current
- Field lines, showing direction of force, are always drawn from north to south.
- Can demonstrate field patterns using iron filings or compass
- Some materials are soft i.e. can magnetise and demagnetise easily e.g. iron. When the m.field is removed, they demagnetise



Concept 1: A current carrying conductor creates a magnetic field

- This can either be straight conductors or solenoids (wires wrapped around a core such as iron).
- Produces electromagnets, used in scrapyards, particle accelerators.
- If alternating current is used, magnetic field alternates.

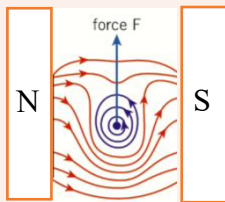


Straight Conductor	Solenoid
<ul style="list-style-type: none">- Use right hand grip rule- Current must be conventional!	<ul style="list-style-type: none">- Use right hand grip rule, but opposite. Thumb is now north pole, fingers is current. <p>Alternatively, if viewed from the sides, the current can be seen going clockwise (S) or anticlockwise (N)</p> <p>North Pole – like an N South Pole – like an S</p>

Concept 2: A current carrying conductor within a permanent m.field experiences a force i.e. Motor Effect

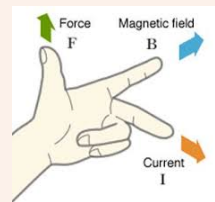
Explanation

- The wire creates a m.field (due to concept 1).
- This interacts with the permanent m.field.
- As they are vectors, they add to create an imbalance in strength above and below the wire. This causes the force on the wire



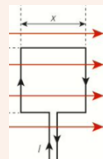
Determining Size and Direction of Force

- The direction of the force can be determined by Flemings LHR. The direction can be switched by switching the direction of the current or the permanent m.field
- $F = BIL\sin\theta$
- Note, max force is when the wire is perpendicular to the field, there is no force if parallel.
- Experimentally, force can be measured by placing wire on weighing scale, tearing, and then applying current, *but remember weighing scales measure reaction force i.e. -ve means the force is downwards, +ve means force is upwards. Convert mass into force using $W=mg$*



Torque of Motor

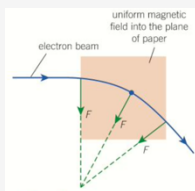
- Can calculate torque since couple (pair of coplanar antiparallel forces on both sides of wire)
- $F = BILx\sin\theta$



Concept 3: A moving charge within a permanent m.field experiences a force causing circular motion

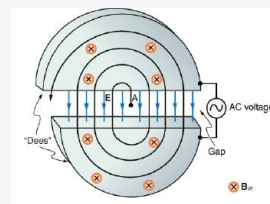
Explanation

- According to FLHR, this force is always perpendicular to the motion of particle
- This creates circular motion.
- Note:- the current finger in FLHR is now the direction of a +ve particle, or opposite to the direction of a -ve particle i.e. conventional
- $F = Bqv\sin\theta$
- Equating to centripetal force: $\frac{mv^2}{r} = Bqv$
- $r = \frac{mv}{Bq} = \frac{p}{Bq}$



Cyclotron Example

- 1) Particle injected in centre. An electric field accelerates the particle across the gap ($F = Eq = ma$)
- 2) Enters an m.field in the dee. This causes circular motion, bringing back into the electric field. No speed increases
- 3) Electric field alternates, causing acceleration towards other dee.
- 4) Process repeats. As particle speeds up, radius of curvature increases until eventual exit.



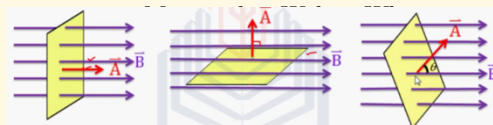
Magnetic Flux Density, B

- Force experienced per unit length of wire carrying 1A.
- Represents magnetic field strength and is a property of magnet
- Think number of field lines per area (how dense)
- Measured in Tesla, T

x Area
→

Magnetic Flux, Φ

- $\Phi = BA\cos\theta$
- Represents field lines acting across area.
- Note $\cos\theta$ is the effective area. When $\theta = 0$, perpendicular so max flux. When $\theta = 90$, parallel so no flux.



x Coils
→

Magnetic Flux Linkage, $N\Phi$

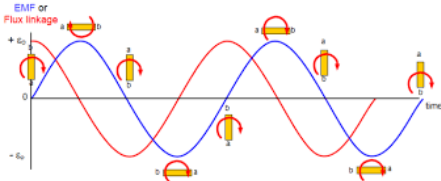
- $N\Phi = BA\cos\theta$
- Represents field lines acting across area across all coils
- Measured in Weber, Wb
- Alternative unit of Weber turns used.

Concept 4: The EMF induced is equal to the rate of change in magnetic flux linkage i.e. Faraday’s Law

- In simple terms, if the conductor experiences a changing magnetic field, an EMF is induced. If a complete circuit, a current is induced.
- This could be by relative motion between the field and the magnet, or by having a conductor in an alternating field (using an a.c. electromagnet)
- $\epsilon = -N \frac{\Delta \Phi}{\Delta t} = -N \frac{\Delta B A \cos(\theta)}{\Delta t}$
- Important: EMF induced does not depend on flux, it depends on the change in flux i.e. the gradient of the flux graph \propto emf induced graph

Example 1 – Rotating Coil (A.C generator)

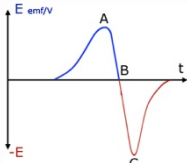
- A rotating coil has changing flux according to $\Phi = BA \cos \theta$
 $= BA \cos(\omega t)$
- Therefore, the EMF is the differential (gradient)
- $\epsilon = -N \frac{\Delta \Phi}{\Delta t} = BAN \sin(\omega t)$
- Assume field going left to right. Notice when coil is vertical, Φ is max but ϵ is zero. When coil is horizontal, Φ is zero but ϵ is max. ϵ is the gradient of Φ .
- Phase difference of $\frac{\pi}{2}$ or 90° . Φ is cos graph, ϵ is sin.



- This is what they use in energy generation. Steam /water drives a turbine, which rotates the coil

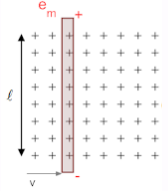
Example 2– Dropping magnet through coil

- Increase in flux when magnet enters coil, no change within coil, and decrease in flux when exiting.
- EMF formed when entering and when exiting.
- Larger EMF when exiting due to same change in flux happening in shorter time (acceleration due to g)



Example 3– Straight Conductor Through Field

- A straight-line conductor of length l moving at velocity v enters a magnetic field of flux density B . EMF increases when enters due to change in flux, then becomes 0 due to no change.
- $\epsilon = Blv$. If rectangular coil $\epsilon = NBlv$ for N coils



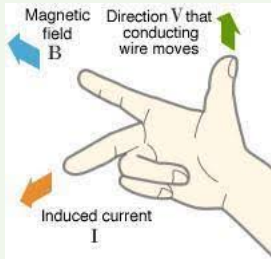
Other Notes

- Ways to increase EMF: Increase velocity, increase B, increase number of coils, increase area of coil.
- Other Examples: Moving magnet in and out of coil (alternating voltage produced), fixed conductor with changing m.field using an ac electromagnet.

Concept 5: The direction of the induced current is such that it opposes the change that created it i.e. Lenz’s Law

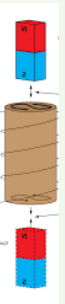
Explanation:

- If we take the example of motor effect, you supply a current to a conductor within a field and this produces a force which causes motion (concept 2)
- Now that there is motion of a conductor within a field, this causes EM induction which creates an induced current, i.e. a generator (concept 4)
- Lenz’s Law: The induced current (and EMF) must be in the opposite direction to the original current. If a clockwise current causes motor effect, the induced current will be anticlockwise. Otherwise, the motor will spin faster and faster as this is a cycle, breaking conservation of energy.
- We refer to the EMF as back EMF and the induced current as eddy currents. This is why there is a -ve in $\epsilon = -N \frac{\Delta \Phi}{\Delta t}$
- We use Flemings Right Hand rule to determine the direction of the induced current (notice how the induced current is opposite to current in FLHR)



Example: Dropping a Magnet into Coil

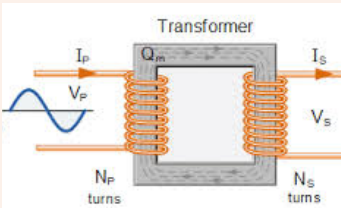
- When the magnet enters, the induced current wants to oppose the change. It is clockwise to create a South Pole at the top of the coil to repel the magnet.
- When the magnet leaves, the induced current at the bottom of the coil will be clockwise to create a South pole to prevent the magnet leaving through attraction.
- Remember, the current is ungrateful, it will be in a direction to create a field that opposes the change that created it!
- A similar case applies to moving a magnet in and out of a coil. It creates a current to generate a field to repel the magnet entering, and then when magnet is leaving, creates a current to generate a field to attract the magnet (prevent it leaving)



Transformers

How They Work

- 1) An alternating current is supplied to the primary coil. This generates an alternating field (concept 1)
- 2) This magnetises and demagnetises the soft iron core, causing a changing magnetic flux to be experienced by the secondary coil.
- 3) This induces an EMF in the secondary coil, proportional to the number of coils (concept 4). If $N_s > N_p$, then voltage increases so step-up. If $N_p > N_s$, then voltage decreases so step-up.



Efficiency

- Efficiency (P_{in}) = P_{out} . If hundred percent efficient, $I_p V_p = I_s V_s$. Therefore, $\frac{V_s}{V_p} = \frac{I_p}{I_s} = \frac{N_s}{N_p}$.
- I.e. stepping up voltage decreases current. We do this in transmission to reduce heat loss via heating effect as $P = I^2 R$
- Careful: The secondary a.c current generates its own magnetic flux that can induce currents backwards due to Lenz’s law.
- To prevent these eddy currents and back emf, we need a material that is magnetic but has high electrical resistance -> laminated iron core.
- The iron is easily magnetised and demagnetised, whilst the insulated sheets (lamination), increases the resistance, decreases eddy currents, and increases efficiency of transformer.